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Stability and Stabilization of Nonlinear Systems



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Shuping He,Xiaoli Luan

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system theory and have some knowledge of switched and hybrid systems to get the most from this monograph **Nonlinear Systems** A. J. Fossard, D. Normand-Cyrot, 1995 Analysis and Synthesis of Nonlinear Control Systems Miguel Bernal, Antonio Sala, Zsófia Lendek, Thierry Marie Guerra, 2022-02-05 This book presents a modern perspective on the modelling analysis and synthesis ideas behind convex optimisation based control of nonlinear systems it embeds them in models with convex structures Analysis and Synthesis of Nonlinear Control Systems begins with an introduction to the topic and a discussion of the problems to be solved It then explores modelling via convex structures including guasi linear parameter varying Takagi Sugeno models and linear fractional transformation structures The authors cover stability analysis addressing Lyapunov functions and the stability of polynomial models as well as the performance and robustness of the models With detailed examples simulations and programming code this book will be useful to instructors researchers and graduate students interested in nonlinear control systems Stabilization of Nonlinear Uncertain Systems Miroslav Krstic, Hua Deng, 1998-05-21 This monograph presents the fundamentals of global stabilization and optimal control of nonlinear systems with uncertain models It offers a unified view of deterministic disturbance attenuation stochastic control and adaptive control for nonlinear systems The book addresses researchers in the areas of robust and adaptive nonlinear control nonlinear H infinity stochastic control and other related areas of control and dynamical systems theory and Stabilization William J. Terrell, 2009-02-15 Stability and Stabilization is the first intermediate level textbook that covers stability and stabilization of equilibria for both linear and nonlinear time invariant systems of ordinary differential equations Designed for advanced undergraduates and beginning graduate students in the sciences engineering and mathematics the book takes a unique modern approach that bridges the gap between linear and nonlinear systems Presenting stability and stabilization of equilibria as a core problem of mathematical control theory the book emphasizes the subject s mathematical coherence and unity and it introduces and develops many of the core concepts of systems and control theory. There are five chapters on linear systems and nine chapters on nonlinear systems an introductory chapter a mathematical background chapter a short final chapter on further reading and appendixes on basic analysis ordinary differential equations manifolds and the Frobenius theorem and comparison functions and their use in differential equations The introduction to linear system theory presents the full framework of basic state space theory providing just enough detail to prepare students for the material on nonlinear systems Focuses on stability and feedback stabilization Bridges the gap between linear and nonlinear systems for advanced undergraduates and beginning graduate students Balances coverage of linear and nonlinear systems Covers cascade systems Includes many examples and exercises Multi-model Jumping Systems: Robust Filtering and Fault Detection Shuping He, Xiaoli Luan, 2021-03-01 This book focuses on multi model systems describing how to apply intelligent technologies to model complex multi model systems by combining stochastic jumping system neural network and fuzzy models It focuses on robust filtering including finite time robust filtering finite frequency robust filtering and higher order

moment robust filtering schemes as well as fault detection problems for multi model jump systems such as observer based robust fault detection filtering based robust fault detection and neural network based robust fault detection methods. The book also demonstrates the validity and practicability of the theoretical results using simulation and practical examples like circuit systems robot systems and power systems. Further it introduces readers to methods such as finite time filtering finite frequency robust filtering as well as higher order moment and neural network based fault detection methods for multi model jumping systems allowing them to grasp the modeling analysis and design of the multi model systems presented and implement filtering and fault detection analysis for various systems including circuit network and mechanical systems

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an overview of the literature in the field and points out directions for further research **Nonlinear Control Systems Design 1992** M. Fliess, 2016-07-07 This volume represents most aspects of the rich and growing field of nonlinear control These proceedings contain 78 papers including six plenary lectures striking a balance between theory and applications Subjects covered include feedback stabilization nonlinear and adaptive control of electromechanical systems nonholonomic systems Generalized state space systems algebraic computing in nonlinear systems theory decoupling linearization and model matching and robust control are also covered Nonlinear Control in the Year 2000 Alberto Isidori, Francoise Lamnabhi-Lagarrigue, Witold Respondek, 2000-11-17 Control of nonlinear systems one of the most active research areas in control theory has always been a domain of natural convergence of research interests in applied mathematics and control engineering The theory has developed from the early phase of its history when the basic tool was essentially only the Lyapunov second method to the present day where the mathematics ranges from differential geometry calculus of variations ordinary and partial differential equations functional analysis abstract algebra and stochastic processes while the applications to advanced engineering design span a wide variety of topics which include nonlinear controllability and observability optimal control state estimation stability and stabilization feedback equivalence motion planning noninteracting control disturbance attenuation asymptotic tracking The reader will find in the book methods and results which cover a wide variety of problems starting from pure mathematics like recent fundamental results on non analycity of small balls and the distance function through its applications to all just mentioned topics of nonlinear control up to industrial applications of nonlinear control algorithms Advances in Stability Theory at the End of the 20th Century A.A. Martynyuk, 2002-10-03 This volume presents surveys and research papers on various aspects of modern stability theory including discussions on modern applications of the theory all contributed by experts in the field The volume consists of four sections that explore the following directions in the development of stability theory progress in stability theory by first approximation contemporary developments in Lyapunov s idea of the direct method the stability of solutions to periodic differential systems and selected applications Advances in Stability Theory at the End of the 20th Century will interest postgraduates and researchers in engineering fields as well as those in mathematics New Directions and Applications in Control Theory Wijesuriya P. Dayawansa, Anders Lindquist, Yishao Zhou, 2005-08-31 This volume contains a collection of papers in control theory and applications presented at a conference in honor of Clyde Martin on the occasion of his 60th birthday held in Lubbock Texas November 14 15 2003

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