

AN OVERVIEW OF SYSTEM IDENTIFICATION METHODS AND APPLICATIONS

PART I: METHODS OF SYSTEM IDENTIFICATION AND DYNAMIC TESTS

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System Identification Methods And Applications

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System Identification Methods And Applications:

Identification of Dynamic Systems Rolf Isermann, Marco Münchhof, 2010-11-22 Precise dynamic models of processes are required for many applications ranging from control engineering to the natural sciences and economics Frequently such precise models cannot be derived using theoretical considerations alone Therefore they must be determined experimentally This book treats the determination of dynamic models based on measurements taken at the process which is known as system identification or process identification Both offline and online methods are presented i e methods that post process the measured data as well as methods that provide models during the measurement The book is theory oriented and application oriented and most methods covered have been used successfully in practical applications for many different processes Illustrative examples in this book with real measured data range from hydraulic and electric actuators up to combustion engines Real experimental data is also provided on the Springer webpage allowing readers to gather their first experience with the methods presented in this book Among others the book covers the following subjects determination of the non parametric frequency response fast Fourier transform correlation analysis parameter estimation with a focus on the method of Least Squares and modifications identification of time variant processes identification in closed loop identification of continuous time processes and subspace methods Some methods for nonlinear system identification are also considered such as the Extended Kalman filter and neural networks The different methods are compared by using a real three mass oscillator process a model of a drive train For many identification methods hints for the practical implementation and application are provided The book is intended to meet the needs of students and practicing engineers working in research and development design and manufacturing System Identification Lennart Ljung, 1998-12-29 The field's leading text now completely updated Modeling dynamical systems theory methodology and applications Lennart Ljung s System Identification Theory for the User is a complete coherent description of the theory methodology and practice of System Identification This completely revised Second Edition introduces subspace methods methods that utilize frequency domain data and general non linear black box methods including neural networks and neuro fuzzy modeling The book contains many new computer based examples designed for Ljung s market leading software System Identification Toolbox for MATLAB Ljung combines careful mathematics a practical understanding of real world applications and extensive exercises He introduces both black box and tailor made models of linear as well as non linear systems and he describes principles properties and algorithms for a variety of identification techniques Nonparametric time domain and frequency domain methods Parameter estimation methods in a general prediction error setting Frequency domain data and frequency domain interpretations Asymptotic analysis of parameter estimates Linear regressions iterative search methods and other ways to compute estimates Recursive adaptive estimation techniques Ljung also presents detailed coverage of the key issues that can make or break system identification projects such as defining objectives designing experiments controlling the bias distribution of transfer function estimates and carefully validating the resulting models The first edition of System Identification has been the field s most widely cited reference for over a decade This new edition will be the new text of choice for anyone concerned with system identification **System Identification** Karel J. Keesman, 2011-05-16 System Identification shows the student reader how to approach the system identification problem in a systematic fashion. The process is divided into three basic steps experimental design and data collection model structure selection and parameter estimation and model validation each of which is the subject of one or more parts of the text Following an introduction on system theory particularly in relation to model representation and model properties the book contains four parts covering data based identification non parametric methods for use when prior system knowledge is very limited time invariant identification for systems with constant parameters time varying systems identification primarily with recursive estimation techniques and model validation methods A fifth part composed of appendices covers the various aspects of the underlying mathematics needed to begin using the text The book uses essentially semi physical or gray box modeling methods although data based transfer function system descriptions are also introduced The approach is problem based rather than rigorously mathematical The use of finite input output data is demonstrated for frequency and time domain identification in static dynamic linear nonlinear time invariant and time varying systems Simple examples are used to show readers how to perform and emulate the identification steps involved in various control design methods with more complex illustrations derived from real physical chemical and biological applications being used to demonstrate the practical applicability of the methods described End of chapter exercises for which a downloadable instructors Solutions Manual is available from fill in URL here will both help students to assimilate what they have learned and make the book suitable for self tuition by practitioners looking to brush up on modern techniques Graduate and final year undergraduate students will find this text to be a practical and realistic course in system identification that can be used for assessing the processes of a variety of engineering disciplines System Identification will help academic instructors teaching control related to give their students a good understanding of identification methods that can be used in the real world without the encumbrance of undue mathematical detail **System Identification: Methods** and Applications Harriet H. Kagiwada, Harriet H. Natsuyama, 1974-01-01 Inverse system identification with applications in predistortion Ylva Jung, 2018-12-19 Models are commonly used to simulate events and processes and can be constructed from measured data using system identification. The common way is to model the system from input to output but in this thesis we want to obtain the inverse of the system Power amplifiers PAs used in communication devices can be nonlinear and this causes interference in adjacent transmitting channels A prefilter called predistorter can be used to invert the effects of the PA such that the combination of predistorter and PA reconstructs an amplified version of the input signal In this thesis the predistortion problem has been investigated for outphasing power amplifiers where the input signal is decomposed into two branches that are amplified separately by highly efficient nonlinear amplifiers and then recombined We

have formulated a model structure describing the imperfections in an outphasing abbrPA and the matching ideal predistorter The predistorter can be estimated from measured data in different ways Here the initially nonconvex optimization problem has been developed into a convex problem The predistorters have been evaluated in measurements The goal with the inverse models in this thesis is to use them in cascade with the systems to reconstruct the original input It is shown that the problems of identifying a model of a preinverse and a postinverse are fundamentally different It turns out that the true inverse is not necessarily the best one when noise is present and that other models and structures can lead to better inversion results To construct a predistorter for a PA for example a model of the inverse is used and different methods can be used for the estimation One common method is to estimate a postinverse and then using it as a preinverse making it straightforward to try out different model structures Another is to construct a model of the system and then use it to estimate a preinverse in a second step This method identifies the inverse in the setup it will be used but leads to a complicated optimization problem A third option is to model the forward system and then invert it This method can be understood using standard identification theory in contrast to the ones above but the model is tuned for the forward system not the inverse Models obtained using the various methods capture different properties of the system and a more detailed analysis of the methods is presented for linear time invariant systems and linear approximations of block oriented systems. The theory is also illustrated in examples When a preinverse is used the input to the system will be changed and typically the input data will be different than the original input This is why the estimation of preinverses is more complicated than for postinverses and one set of experimental data is not enough Here we have shown that identifying a preinverse in series with the system in repeated experiments can improve the inversion performance Application of System Identification in Engineering H.G. Natke, 2014-05-04 System identification is a powerful tool in engineering Its various methods in the frequency and in the time domain have been extensively discussed in earlier CISM courses The aim of this course is to describe the state of the art in specific application areas such as estimation of eigenquantities in the aerospace industry in civil engineering in naval engineering etc noise source detection fault detection by investigation of dynamic properties such as machine sound characteristics and the identification of the dynamic behaviour of flow induced systems e g aerolastic problems Geotechnical applications are also among the fields of interest The lecture notes contain demonstrations of several methods and include a valuation by combining various kinds of experience Such complex information includes not only theoretical aspects of identification but also advice on practical handling for example concerning testing effort and data handling **Applications** of Quasilinearization Theory to System Identification George A. Zupp, Bart Childs, 1969 Control and Dynamic Systems V56: Digital and Numeric Techniques and Their Application in Control Systems C.T. Leonides, 2012-12-02 Control and Dynamic Systems Advances in Theory and Applications Volume 56 Digital and Numeric Techniques and their Applications in Control Systems Part 2 of 2 covers the significant developments in digital and numerical techniques for the analysis and

design of modern complex control systems This volume is composed of 12 chapters and starts with a description of the design techniques of linear constrained discrete time control systems The subsequent chapters describe the techniques dealing with robust real time system identification the adaptive control algorithms and the utilization of methods from generalized interpolation and operator theory to deal with a wide range of problems in robust control These topics are followed by reviews f the decentralized control design for interconnected uncertain systems the computation of frequency response of descriptor systems by rational interpolation the techniques for the synthesis of multivariable feedback control laws and the effect of the initial condition in state estimation for discrete time linear systems Other chapters illustrate practical efficient and reliable numerical algorithms for robust multivariable control design of linear time invariant systems as well as a complete analysis of closed loop transfer recovery in discrete time systems using observer based controllers The last chapters provide the techniques in robust policy making in the global economic environment and the implications of robust control techniques for continuous time systems This book will prove useful to process control systems and design engineers

Simulation Techniques of Digital Twin in Real-Time Applications Abhineet Anand, Anita Sardana, Abhishek Kumar, Srikanta Kumar Mohapatra, Shikha Gupta, 2024-06-26 SIMULATION TECHNIQUES OF DIGITAL TWIN IN REAL TIME APPLICATIONS The book gives a complete overview of implementing digital twin technology in real time scenarios while emphasizing how this technology can be embedded with running technologies to solve all other issues Divided into two parts with Part 1 focusing on simulated techniques in digital twin technology and Part 2 on real time applications of digital twin technology the book collects a significant number of important research articles from domain specific experts The book sheds light on the various techniques of digital twin technology that are implemented in various application areas It emphasizes error findings and respective solutions before the actual event happens Most of the features in the book are on the implementation of strategies in real time applications Various real life experiences are taken to show the proper implementation of simulation technologies The book shows how engineers of any technology can input their research ideas to convert to real scenarios by using replicas Hence the book has a collection of research articles from various engineers with expertise in different technologies from many regions of the world It shows how to implement the embedded real time data into technologies Specifically the chapters relate to the auto landing and cruising features in aerial vehicles automated coal mining simulation strategy the enhancement of workshop equipment and implementation in power energy management for urban railways This book also describes the coherent mechanism of digital twin technologies with deep neural networks and artificial intelligence Audience Researchers engineers and students in computer science software engineering and industrial engineering will find this book to be very useful **System Identification** R. Isermann, 2014-05-23 System Identification is a special section of the International Federation of Automatic Control IFAC Journal Automatica that contains tutorial papers regarding the basic methods and procedures utilized for system identification Topics include modeling and identification step response and

frequency response methods correlation methods least squares parameter estimation and maximum likelihood and prediction error methods After analyzing the basic ideas concerning the parameter estimation methods the book elaborates on the asymptotic properties of these methods and then investigates the application of the methods to particular model structures. The text then discusses the practical aspects of process identification which includes the usual general procedures for process identification selection of input signals and sampling time offline and on line identification comparison of parameter estimation methods data filtering model order testing and model verification Computer program packages are also discussed. This compilation of tutorial papers aims to introduce the newcomers and non specialists in this field to some of the basic methods and procedures used for system identification

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