Stability and Control: Theory, Methods and Applications

Stabilization of Programmed Motion

E. Ya. Smirnov

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Stabilization Of Programmed Motion

Yu. A. Mitropolsky, A.M. Samoilenko, V.L. Kulik

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Stability and Stabilization of Nonlinear Systems with Random Structures I. Ya Kats, A.A. Martynyuk, 2002-08-22 Nonlinear systems with random structures arise guite frequently as mathematical models in diverse disciplines This monograph presents a systematic treatment of stability theory and the theory of stabilization of nonlinear systems with random structure in terms of new developments in the direct Lyapunov s method The analysis focuses on dynamic systems with random Markov parameters This high level research text is recommended for all those researching or studying in the fields of applied mathematics applied engineering and physics particularly in the areas of stochastic differential equations D.I. Nwokah, 2017-12-19 With a specific focus on the needs of the designers and engineers in industrial settings The Mechanical Systems Design Handbook Modeling Measurement and Control presents a practical overview of basic issues associated with design and control of mechanical systems In four sections each edited by a renowned expert this book answers diverse questions fundamental to the successful design and implementation of mechanical systems in a variety of applications Manufacturing addresses design and control issues related to manufacturing systems From fundamental design principles to control of discrete events machine tools and machining operations to polymer processing and precision manufacturing systems Vibration Control explores a range of topics related to active vibration control including piezoelectric networks the boundary control method and semi active suspension systems Aerospace Systems presents a detailed analysis of the mechanics and dynamics of tensegrity structures Robotics offers encyclopedic coverage of the control and design of robotic systems including kinematics dynamics soft computing techniques and teleoperation Mechanical systems designers and engineers have few resources dedicated to their particular and often unique problems The Mechanical Systems Design Handbook clearly shows how theory applies to real world challenges and will be a welcomed and valuable addition to your Stability of Differential Equations with Aftereffect N.V. Azbelev, P.M. Simonov, 2002-10-03 Stability of Differential library Equations with Aftereffect presents stability theory for differential equations concentrating on functional differential equations with delay integro differential equations and related topics. The authors provide background material on the

modern theory of functional differential equations and introduce some new flexible methods for investigating the asymptotic behaviour of solutions to a range of equations The treatment also includes some results from the authors research group based at Perm and provides a useful reference text for graduates and researchers working in mathematical and engineering <u>Dynamics And Robust Control Of Robot-environment Interaction</u> Miomir Vukobratovic, Dragoljub Surdilovic, Yury science Ekalo, Dusko Katic, 2009-03-06 This book covers the most attractive problem in robot control dealing with the direct interaction between a robot and a dynamic environment including the human robot physical interaction It provides comprehensive theoretical and experimental coverage of interaction control problems starting from the mathematical modeling of robots interacting with complex dynamic environments and proceeding to various concepts for interaction control design and implementation algorithms at different control layers Focusing on the learning principle it also shows the application of new and advanced learning algorithms for robotic contact tasks The ultimate aim is to strike a good balance between the necessary theoretical framework and practical aspects of interactive robots **Control of Nonlinear** Mechanical Systems Jan M. Skowronski, 2012-12-06 A modern mechanical structure must work at high speed and with high precision in space and time in cooperation with other machines and systems All this requires accurate dynamic modelling for instance recognizing Coriolis and centrifugal forces strong coupling effects flexibility of links large angles articulation This leads to a motion equation which must be highly nonlinear to describe the reality r1oreover work on the manufacturing floor requires coordination between nachines between each machine and a conveyor and demands robustness of the controllers against uncertainty in payload gravity external perturbations etc This requires adaptive controllers and system coordination and perhaps a self organizing structure The machines become complex strongly nonlinear and strongly coupled mechanical systems with many degrees of freedom controlled by sophisticated mathematical programs. The design of such systems needs basic research in Control and System Dynamics as well as in Decision Making Theory Dynamic Games not only in the use of these disciplines but in their adjustment to the present demand This in turn generates the need to prepare engineering students for the job by the teaching of more sophisti cated techniques in control and Mechanics than those contained in previous curricula On the other hand all that was mentioned above regarding the design of machines applies equally well to other presently designed and used mechan ical structures or systems Dichotomies and Stability in Nonautonomous Linear Systems Yu. A. Mitropolsky, A.M. Samoilenko, V.L. Kulik, 2002-10-10 Linear nonautonomous equations arise as mathematical models in mechanics chemistry and biology The investigation of bounded solutions to systems of differential equations involves some important and challenging problems of perturbation theory for invariant toroidal manifolds This monograph is a detailed study of the application of Lyapunov functions with variable sign expressed in quadratic forms to the solution of this problem The authors explore the preservation of invariant tori of dynamic systems under perturbation This volume is a classic contribution to the literature on stability theory and provides a useful source of reference for

postgraduates and researchers Asymptotic Methods in Resonance Analytical Dynamics Eugeniu Grebenikov, Yu. A. Mitropolsky, Y.A. Ryabov, 2004-03-02 Asymptotic Methods in Resonance Analytical Dynamics presents new asymptotic methods for the analysis and construction of solutions mainly periodic and quasiperiodic of differential equations with small parameters Along with some background material and theory behind these methods the authors also consider a variety of problems and applications in nonlinear mechanics and oscillation theory. The methods examined are based on two types the generalized averaging technique of Krylov Bogolubov and the numeric analytical iterations of Lyapunov Poincar This text provides a useful source of reference for postgraduates and researchers working in this area of applied mathematics

Stabilisation and Motion Control of Unstable Objects Alexander M. Formalskii,2015-11-13 Systems with mechanical degrees of freedom containing unstable objects are analysed in this monograph and algorithms for their control are developed discussed and numerically tested This is achieved by identifying unstable modes of motion and using all available resources to suppress them By using this approach the region of states from which a stable regime can be reached is maximised The systems discussed in this book are models for pendula and vehicles and find applications in mechatronics robotics as well as in mechanical and automotive engineering

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