

E. Rogers, D.H. Owens

**Stability Analysis
for Linear Repetitive
Processes**



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Stability Analysis For Linear Repetitive Processes
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Volume 175

Eric Rogers, David H. Owens



Stability Analysis For Linear Repetitive Processes Lecture Notes In Control And Information Sciences Volume 175:

Topics in Operator Theory Joseph A. Ball, Vladimir Bolotnikov, J. William Helton, Leiba Rodman, Ilya M.

Spitkovsky, 2011-02-03 This is the second volume of a collection of original and review articles on recent advances and new directions in a multifaceted and interconnected area of mathematics and its applications It encompasses many topics in theoretical developments in operator theory and its diverse applications in applied mathematics physics engineering and other disciplines The purpose is to bring in one volume many important original results of cutting edge research as well as authoritative review of recent achievements challenges and future directions in the area of operator theory and its applications

Control Systems Theory and Applications for Linear Repetitive Processes Eric Rogers, Krzysztof Galkowski, David H. Owens, 2007-02-20 After motivating examples this monograph gives substantial new results on the analysis and control of linear repetitive processes These include further applications of the abstract model based stability theory which in particular shows the critical importance to the dynamics developed of the structure of the initial conditions at the start of each new pass the development of stability tests and performance bounds in terms of so called 1D and 2D Lyapunov equations It presents the development of a major bank of results on the structure and design of control laws including the case when there is uncertainty in the process model description together with numerically reliable computational algorithms Finally the application of some of these results in the area of iterative learning control is treated including experimental results from a chain conveyor system and a gantry robot system

Stability Analysis for Linear Repetitive Processes Eric Rogers, David H. Owens, 1992 Industrial processes such as long wall coal cutting and metal rolling together with certain areas of 2D signal and image processing exhibit a repetitive or multipass structure characterized by a series of sweeps of passes through a known set of dynamics The output or pass profile produced on each pass explicitly contributes to that produced on the next This interpass interaction can lead to the growth of oscillations and hence a form of instability in the sequence of pass profiles which require control strategies that explicitly incorporate the essential repetitive structure of the process in their decision making This monograph is unique in developing the new techniques necessary for systematic control systems design in the form of a stability theory and computationally feasible stability tests based on finite simulations and polynomial analysis Its development requires a basic knowledge of linear frequency domain and state space theory and a knowledge of basic functional analysis would be beneficial The text is aimed at researchers in the area of control and systems theory and should also be of interest to those working in the related area of signal and image processing

Multidimensional Systems Theory and Applications N.K. Bose, 2013-12-20 Preface to Second Edition From the time that the original edition was published in 1985 multidimensional systems theory has matured into a discipline of research and teaching with an expanding array of applications The international journal on Multidimensional Systems and Signal

Processing founded in 1990 is now in its fourteenth year A biannual international workshop on n D systems was launched in 1998 and the impressive number of special sessions mini symposia monographs and special issues that have emerged bear testimony to the growing popularity and importance of the subject matter among scientists in various disciplines including engineering computer science geophysics and mathematics This second edition builds on the fundamentals expounded in the original book with the addition of important developments in theory as well as practice since 1985 Particular attention has been given to the consolidation of basic results unification of theory and the diversification of applications Chapters that remain have been reordered and updated in content and references Some chapters considered to be somewhat outdated have been replaced with newer proven as well as potentially significant results inspired by some groundbreaking research and directions which are likely to stimulate further research In addition to the description of some challenging open problems posed in 1985 which have since been solved new problems yet to be tackled are also included

Filtering and Control for Classes of Two-Dimensional Systems Ligang Wu, Zidong Wang, 2015-01-09 This book focuses on filtering control and model reduction problems for two dimensional 2 D systems with imperfect information The time delayed 2 D systems covered have system parameters subject to uncertain stochastic and parameter varying changes After an initial introduction of 2 D systems and the ideas of linear repetitive processes the text is divided into two parts detailing General theory and methods of analysis and optimal synthesis for 2 D systems and Application of the general theory to the particular case of differential discrete linear repetitive processes The methods developed provide a framework for stability and performance analysis optimal and robust controller and filter design and model approximation for the systems considered Solutions to the design problems are couched in terms of linear matrix inequalities For readers interested in the state of the art in linear filtering control and model reduction *Filtering and Control for Classes of Two Dimensional Systems* will be a useful reference for exploring the field of 2 D systems either from a purely theoretical research perspective or from the point of view of a multitude of potential applications including image processing and the study of seismographic data or thermal processes

Information Processing and Security Systems Khalid Saeed, Jerzy Pejas, 2005-12-06 Information Processing and Security Systems is a collection of forty papers that were originally presented at an international multi conference on Advanced Computer Systems ACS and Computer Information Systems and Industrial Management Applications CISIM held in Elk Poland This volume describes the latest developments in advanced computer systems and their applications within artificial intelligence biometrics and information technology security The volume also includes contributions on computational methods algorithms and applications computational science education and industrial management applications

State-space Realisations of Linear 2-D Systems with Extensions to the General ND ($n > 2$) Case Krzysztof Galkowski, 2001 This book demonstrates the newly developed Elementary Operations Algorithm EOA This is a systematic method for constructing a range of state space realizations for 2 D systems The key achievements of the monograph are as

follows It provides a research level introduction to the general area and undertakes a comparative critical review of previous approaches It gives a thorough coverage of the theoretical basis of the EOA algorithm It demonstrates the effectiveness of the EOA algorithm for example through the use of algebraic symbolic computing using MAPLE as well as by comparing this method with common alternatives

Multidimensional Signals, Circuits and Systems Krzysztof Galkowski, Jeff David Wood, 2001-05-10 Although research on general multidimensional systems theory has been developing rapidly in recent years this is the first research text to appear on the subject since the early 1980s The text describes the current state of the art nD systems and sets out a number of open problems and gives several different perspectives on the subject It presents a number of different solutions to major theoretical problems as well as some interesting practical results The book comprises of a selection of plenary and other lectures given at The First International Workshop on Multidimensional nD Systems NDS 98 held in 1998 in Poland and is written by leading world specialists in the field

Numerical Linear Algebra in Signals, Systems and Control Paul Van Dooren, Shankar P. Bhattacharyya, Raymond H. Chan, Vadim Olshevsky, Aurobinda Routray, 2011-05-21 The purpose of Numerical Linear Algebra in Signals Systems and Control is to present an interdisciplinary book blending linear and numerical linear algebra with three major areas of electrical engineering Signal and Image Processing and Control Systems and Circuit Theory Numerical Linear Algebra in Signals Systems and Control will contain articles both the state of the art surveys and technical papers on theory computations and applications addressing significant new developments in these areas The goal of the volume is to provide authoritative and accessible accounts of the fast paced developments in computational mathematics scientific computing and computational engineering methods applications and algorithms The state of the art surveys will benefit in particular beginning researchers graduate students and those contemplating to start a new direction of research in these areas A more general goal is to foster effective communications and exchange of information between various scientific and engineering communities with mutual interests in concepts computations and workable reliable practices

Proceedings of the Fourth International Colloquium on Differential Equations Drumi D. Bainov, V. Covachev, 1994 The Fourth International Colloquium on Differential Equations was organized by UNESCO and the Plovdiv Technical University with the help of many international mathematical organizations and was held in Plovdiv Bulgaria 18 22 August 1993 This proceedings volume contains selected invited talks which deal with the following topics impulsive differential equations nonlinear differential equations differential equations with maxima applications of differential equations

Advances in Control Paul M. Frank, 2012-12-06 Advances in Control contains keynote contributions and tutorial material from the fifth European Control Conference held in Germany in September 1999 The topics covered are of particular relevance to all academics and practitioners in the field of modern control engineering These include Modern Control Theory Fault Tolerant Control Systems Linear Descriptor Systems Generic Robust Control Design Verification of Hybrid Systems New Industrial Perspectives Nonlinear System Identification Multi Modal

Telepresence Systems Advanced Strategies for Process Control Nonlinear Predictive Control Logic Controllers of Continuous Plants Two dimensional Linear Systems This important collection of work is introduced by Professor P M Frank who has almost forty years of experience in the field of automatic control State of the art research expert opinions and future developments in control theory and its industrial applications combine to make this an essential volume for all those involved in control engineering

Predictive Learning Control for Unknown Nonaffine Nonlinear Systems Qiongxia Yu, Ting Lei, Fengchen Tian, Zhongsheng Hou, Xuhui Bu, 2023-02-17 This book investigates both theory and various applications of predictive learning control PLC which is an advanced technology for complex nonlinear systems To avoid the difficult modeling problem for complex nonlinear systems this book begins with the design and theoretical analysis of PLC method without using mechanism model information of the system and then a series of PLC methods is designed that can cope with system constraints varying trial lengths unknown time delay and available and unavailable system states sequentially Applications of the PLC on both railway and urban road transportation systems are also studied The book is intended for researchers engineers and graduate students who are interested in predictive control learning control intelligent

transportation systems and related fields European Control Conference 1995, 1995-09-05 Proceedings of the European Control Conference 1995 Rome Italy 5 8 September 1995 Progress in Industrial Mathematics at ECMI 94 Helmut

Neunzert, 2013-03-09 Aerospace Industry Some Applications of Mathematics in Aeronautics and Perspectives invited paper Small Satellites for Deep Space Operation a Challenge to Optimal Control Numerical Computation of Optimal Ascent Trajectories with a Dynamic Pressure Limit Real Time Optimisation for the Guidance of Dynamic Systems Time Discrete Event Systems and Time Tables Parallel Computation in Air Traffic Guidance The Numerical Investigation of the Two dimensional Shock Wave Reflection Automotive Industry The Direct Modification of Surface Curvatures in Car Body Design invited paper **Inversion Method in the Discrete-time Nonlinear Control Systems Synthesis Problems** Ülle

Kotta, 2006-01-21 The purpose of this book is twofold To survey control system design methods based on the system inversion technique and to collect into one place the many recent results in the field It has been known for some time that inverse systems may be used to solve numerous control problems Despite the importance and conceptual simplicity of this topic there appears to be no monograph written on it The purpose of this work is therefore to present and apply a systematic design method which bases itself on the fundamental system property of invertibility Many different theoretical and practical aspects are considered in this volume working from elementary topics in the first section to current research in the second

Balanced Control of Flexible Structures Wodek Gawronski, 2006-04-10 Methods of structural control and dynamics are introduced in this book These include reduction of large structural models by balanced truncation placement of actuators and sensors for dynamic testing and control structural identification of the minimum order balanced representation balanced dissipative controller design balanced LQG and H controller designs with the closed form relationships between controller

parameters and system performance and controller reduction methods that preserve the closed loop performance The book explores the unique properties of flexible structures to obtain efficient methods of dynamic analysis and controller design The presented methods of structural dynamics identification sensor actuator placement and passive LQG and H controller design have been checked both with simulations and industrial implementations **ISIE'96**, 1996 **Parallel Processing in a Control Systems Environment** Eric Rogers, Yun Li, 1993 This survey covers the area of parallel processing which is increasing in importance due to advances in the design and implementation of control automation systems A range of work is covered and potential directions for future developments are examined **Proceedings, IEEE Control Systems Society ... Symposium on Computer-Aided Control System Design (CACSD)**, 1999 Progress in System and Robot Analysis and Control Design Spyros G. Tzafestas, 1999-05-14 The fields of control and robotics are now at an advanced level of maturity both in theory and practice Numerous systems are used effectively in industrial production and other sectors of modern life This volume contains a well balanced collection of over fifty papers focusing on analysis and design problems The current trends and advances in the fields are reflected Topics covered include system analysis identification and stability optimal adaptive robust and QFT controller design design and application of driving simulators industrial robots and telemanipulators mobile service and legged robots virtual reality in robotics The book brings together important original results derived from a variety of academic and engineering environments Also it serves as a timely reference volume for the researcher and practitioner

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