

Dr. Rega Rajendra did Bachelor and Master degrees in Mechanical Engineering with Specialization in Production Engineering at University College of Engineering, Osmania University, Hyderabad, India, and pursued PhD programme at Indian Institute of Technology Kharagpur, India. He has keen interest in Soft Computing applications to Robotics. He is currently working in Osmania University, Hyderabad, India. Prof. D.K. Pratihar received his Ph.D. from IIT Kanpur, India in 2000. He received University Gold Medal, A.M. Das Memorial Medal, Institution of Engineers' (I) Medal, and others. He completed his post-doctoral studies in Germany under the AaM Fellowship Programme. He is working as a Professor of IIT Kharagpur, India. His research areas include robotics, soft computing and manufacturing science. He has published more than 150 papers. He has written a textbook on "Soft Computing", co-authored another textbook on "Analytical Engineering Mechanics", edited a book on "Intelligent and Autonomous Systems", co-authored a reference book on "Modeling and Analysis of Scaled Robots". He is in editorial board of ten International



Rega Rajendra
Dilip Kumar Pratihar

Modeling and Simulations of Robotic Systems using Soft Computing

Robotics and Intelligent Systems

Rega Rajendra

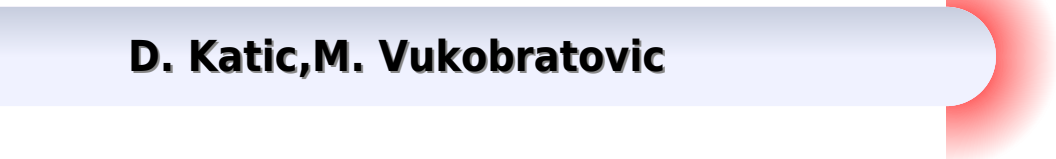
Dr. Rega Rajendra pursued PhD programme at Indian Institute of Technology Kharagpur, India. His main interests are in the field of manufacturing and metrology. He has keen interest in Soft Computing applications to Robotics. He is currently working in Osmania University, India.



978-3-659-26483-2

Soft Computing For Intelligent Robotic Systems

D. Katic, M. Vukobratovic



Soft Computing For Intelligent Robotic Systems:

Soft Computing for Intelligent Robotic Systems Toshio Fukuda,1998-12-04 Research results using some of the most advanced soft computing techniques in intelligent robotic systems are presented The main purpose of this book is to show how the power of soft computing techniques can be exploited in intelligent robotic systems The main emphasis is on control system for a mobile robot behavior arbitration for a mobile robot reinforcement learning of a robot manipulation of a robot collision avoidance and automatic design of robots This book will be useful for application engineers scientists and researchers who wish to use some of the most advanced soft computing techniques in robotics

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Intelligent Control of Robotic Systems D. Katic,M. Vukobratovic,2013-03-14 As robotic systems make their way into standard practice they have opened the door to a wide spectrum of complex applications Such applications usually demand that the robots be highly intelligent Future robots are likely to have greater sensory capabilities more intelligence higher levels of manual dexterity and adequate mobility compared to humans In order to ensure high quality control and performance in robotics new intelligent control techniques must be developed which are capable of coping with task complexity multi objective decision making large volumes of perception data and substantial amounts of heuristic information Hence the pursuit of intelligent autonomous robotic systems has been a topic of much fascinating research in recent years On the other hand as emerging technologies Soft Computing paradigms consisting of complementary elements of Fuzzy Logic Neural Computing and Evolutionary Computation are viewed as the most promising methods towards intelligent robotic systems Due to their strong learning and cognitive ability and good tolerance of uncertainty and imprecision Soft Computing techniques have found wide application in the area of intelligent control of robotic systems

Autonomous Robotic Systems Changjiu Zhou,Darío Maravall,Da Ruan,2013-03-20 This book contains an

edited collection of eighteen contributions on soft and hard computing techniques and their applications to autonomous robotic systems Each contribution has been exclusively written for this volume by a leading researcher The volume demonstrates the various ways that the soft computing and hard computing techniques can be used in different integrated manners to better develop autonomous robotic systems that can perform various tasks of vision perception cognition thinking pattern recognition decision making and reasoning and control amongst others Each chapter of the book is self contained and points out the future direction of research It is a must reading for students and researchers interested in exploring the potentials of the fascinating field that will form the basis for the design of the intelligent machines of the future Madan M Gupta **Aspects of Soft Computing, Intelligent Robotics and Control** János Fodor, 2009-10-13 Soft computing as a collection of techniques exploiting approximation and tolerance for imprecision and uncertainty in traditionally intractable problems has become very effective and popular especially because of the synergy derived from its components The integration of constituent technologies provides complementary methods that allow developing flexible computing tools and solving complex problems A wide area of natural applications of soft computing techniques consists of the control of dynamic systems including robots Loosely speaking control can be understood as driving a process to attain a desired goal Intelligent control can be seen as an extension of this concept to include autonomous human like interactions of a machine with the environment Intelligent robots can be characterized by the ability to operate in an uncertain changing environment with the help of appropriate sensing They have the power to autonomously plan and execute motion sequences to achieve a goal specified by a human user without detailed instructions In this volume leading specialists address various theoretical and practical aspects in soft computing intelligent robotics and control The problems discussed are taken from fuzzy systems neural networks interactive evolutionary computation intelligent mobile robotics and intelligent control of linear and nonlinear dynamic systems **Soft Computing in Advanced Robotics** Yong-Tae Kim, Ichiro Kobayashi, Euntai Kim, 2014-07-08 Intelligent system and robotics are inevitably bound up intelligent robots makes embodiment of system integration by using the intelligent systems We can figure out that intelligent systems are to cell units while intelligent robots are to body components The two technologies have been synchronized in progress Making leverage of the robotics and intelligent systems applications cover boundlessly the range from our daily life to space station manufacturing healthcare environment energy education personal assistance logistics This book aims at presenting the research results in relevance with intelligent robotics technology We propose to researchers and practitioners some methods to advance the intelligent systems and apply them to advanced robotics technology This book consists of 10 contributions that feature mobile robots robot emotion electric power steering multi agent fuzzy visual navigation adaptive network based fuzzy inference system swarm EKF localization and inspection robot This edition is published in original peer reviewed contributions covering from initial design to final prototypes and authorization **Design and Control of Intelligent Robotic Systems** Dikai

Liu, Lingfeng Wang, Kay Chen Tan, 2009-03-05 With the increasing applications of intelligent robotic systems in various fields the sign and control of these systems have increasingly attracted interest from researchers This edited book entitled Design and Control of Intelligent Robotic Systems in the book series of Studies in Computational Intelligence is a collection of some advanced research on design and control of intelligent robots The works presented range in scope from design methodologies to robot development Various design approaches and algorithms such as evolutionary computation neural networks fuzzy logic learning etc are included We also would like to mention that most studies reported in this book have been implemented in physical systems An overview on the applications of computational intelligence in bio inspired robotics is given in Chapter 1 by M Begum and F Karray with highlights of the recent progress in bio inspired robotics research and a focus on the usage of computational intelligence tools to design human like cognitive abilities in the robotic systems In Chapter 2 Lisa L Grant and Ganesh K Venayagamoorthy present greedy search particle swarm optimization and fuzzy logic based strategies for navigating a swarm of robots for target search in a hazardous environment with potential applications in high risk tasks such as disaster recovery and hazardous material detection Aspects of Soft Computing, Intelligent Robotics and Control János Fodor, 2009-08-20 Soft computing as a collection of techniques exploiting approximation and tolerance for imprecision and uncertainty in traditionally intractable problems has become very effective and popular especially because of the synergy derived from its components The integration of constituent technologies provides complementary methods that allow developing flexible computing tools and solving complex problems A wide area of natural applications of soft computing techniques consists of the control of dynamic systems including robots Loosely speaking control can be understood as driving a process to attain a desired goal Intelligent control can be seen as an extension of this concept to include autonomous human like interactions of a machine with the environment Intelligent robots can be characterized by the ability to operate in an uncertain changing environment with the help of appropriate sensing They have the power to autonomously plan and execute motion sequences to achieve a goal specified by a human user without detailed instructions In this volume leading specialists address various theoretical and practical aspects in soft computing intelligent robotics and control The problems discussed are taken from fuzzy systems neural networks interactive evolutionary computation intelligent mobile robotics and intelligent control of linear and nonlinear dynamic systems **Modeling and Simulations of Robotic Systems Using Soft Computing** Rega Rajendra, Dilip Kumar Pratihar, 2012-10-06

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