SIX LECTURES ON DYNAMICAL SYSTEMS

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Six Lectures On Dynamical Systems

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Six Lectures On Dynamical Systems:

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Topological feedback entropy and nonlinear stabilization IEEE Trans Automat Control 49 2004 1585 1597 The book presents the foundations of a theory which aims at finding expressions for invariance entropy in terms of dynamical quantities such as Lyapunov exponents While both discrete time and continuous time systems are treated the emphasis lies on systems given by differential equations

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