Smart Robots

Sundaravadivazhagan Balasubramanian,Gnanasankaran Natarajan,Pethuru Raj Chelliah

Smart Robots:

   Smart Robots V. Hunt,2013-03-07 Here is one of the first really thorough presentations on smart robots Robots machine vision systems sensors manipulators expert systems and artificial intelligence concepts combined in state of the art computer integrated manufacturing systems These smart robots increase produc tivity and improve the quality of our products This comprehensive volume which is extensively illustrated provides a unique synthesis and overview of the emerging field of smart robots the basic approaches for each of the constituents systems the techniques used applications the descriptions of current hardware or software projects a review of the state of the art of the technology current research and development efforts and trends in the development of smart robots All of the information has been compiled from a wide variety of knowledgeable sources and recent government reports An extensive selection of photo graphs diagrams and charts amplify this book The contents of major chapters include Introduction to smart robots Artificial intelligence for smart robots Smart robot systems Sensor controlled robots Machine vision systems Robot manipulators Natural language processing Expert systems and Computer integrated manufacturing Smart Robots presents the state of the art in intelligent robots It is designed to help the reader develop an understanding of industrial applications of smart robots as well as the new technological develop ments Smart Robots is an outstanding introduction to the integration and application of machine vision systems sensors expert systems and artificial intelligence technology   **Building Smart Robots Using ROS** Robin Tommy,Ajithkumar Narayanan Manaparampil,Rinu Michael,2022-03-24 A beginner s guide to learn ROS robotics platform and practice building robotics system KEY FEATURES A step by step guide covering the robot s design assembly navigation and control Numerous techniques ROS packages object detection and image processing concepts included Practical exercises and sample codes to robotics design simulation and visualization tools DESCRIPTION This book is a practical introduction to the Robotics operating system ROS It will expose you to the essential principles tools and packages in ROS and assist you in configuring and recombining components for additional tasks If you are new to the world of robotics you will enjoy the companionship of this book as it guides you through the process of building your first robot The book introduces robotics and advances through numerous concepts such as sensors and actuators SLAM Aruco markers CAD computer aided design React native application development image processing in ROS machine learning and object detection Every point raised above is illustrated in a live robotics environment Along the way other packages required for developing ROS apps will be presented including serial OpenCV and cv bridge You ll learn about tools like SolidWorks Moveit Rviz as well as simulation platforms like gazebo and turtlesim which will give you a complete picture of what it takes to build a robot This book presents an in depth examination of Robot Operating Systems ROS the sole foundation for developing robotics applications The book guides the readers through investigating and embedding machine learning code to introduce intelligence into the robot WHAT YOU WILL LEARN Develop a stronghold on basics of robotics with code samples and

illustrations Familiarity with ROS the configuration of nodes and 3D robot simulations Learn how to publish data to the ROS network for web integration Learn about SLAM CAD React Native and ROS image processing Learn about Artificial Intelligence principles and object detection with ROS Complete design simulation and assembly of a robot WHO THIS BOOK IS FOR The book is aimed at robotics developers hardware product designers full stack application developers machine learning enthusiasts and students who want to obtain real world experience in robotics development from start to finish Having some experience with Ubuntu and the python programming language would be helpful TABLE OF CONTENTS 1 ROS 2 Writing Nodes 3 Sensors and Actuators 4 ROS SERIAL 5 Web interface 6 Turtle Sim Simulation 7 Designing a robot 8 Gazebo 9 Moveit 10 Rviz 11 Vision 12 Aruco Markers 13 SLAM 14 React Native App 15 Artificial Intelligence <u>Building Smart LEGO MINDSTORMS EV3 Robots</u> Kyle Markland,2018-04-04 Build and program smart robots with the EV3 Key Features Efficiently build smart robots with the LEGO MINDSTORMS EV3 Discover building techniques and programming concepts that are used by engineers to prototype robots in the real world This project based guide will teach you how to build exciting projects such as the objecta tracking tank ultimate all terrain vehicle remote control race car or even a GPS navigating autonomous vehicle Book Description Smart robots are an ever increasing part of our daily lives With LEGO MINDSTORMS EV3 you can now prototype your very own small scale smart robot that uses specialized programming and hardware to complete a mission EV3 is a robotics platform for enthusiasts of all ages and experience levels that makes prototyping robots accessible to all This book will walk you through six different projects that range from intermediate to advanced level The projects will show you building and programming techniques that are used by engineers in the real world which will help you build your own smart robot You ll see how to make the most of the EV3 robotics platform and build some awesome smart robots The book starts by introducing some real world examples of smart robots Then we ll walk you through six different projects and explain the features that allow these robots to make intelligent decisions The book will guide you as you build your own object tracking tank a box climbing robot an interactive robotic shark a quirky bipedal robot a speedy remote control race car and a GPS navigating robot By the end of this book you ll have the skills necessary to build and program your own smart robots with EV3 What you will learn Understand the characteristics that make a robot smart Grasp proportional beacon following and use proximity sensors to track an object Discover how mechanisms such as rack and pinion and the worm gear work Program a custom GUI to make a robot more user friendly Make a fun and quirky interactive robot that has its own personality Get to know the principles of remote control and programming car style steering Understand some of the mechanisms that enable a car to drive Navigate to a destination with a GPS receiver Who this book is for This book is for hobbyists robotic engineers and programmers who understand the basics of the EV3 programming language and are familiar with building with LEGO Technic and want to try some advanced projects If you want to learn some new engineering techniques and take your experience with the EV3 to the next level then this book is for you

Intelligent Educational Robots Stamatios Papadakis,Georgios Lampropoulos,2024-12-16 This book focuses on recent advances in maker education and in human robot interaction and on the integration of intelligent educational robots IER in P 12 education It covers various topics and trends about the evolution of maker education and the use of IER and artificial intelligence AI in P 12 education This book offers an overview of recent research into the adoption integration advancements and impact of IER and AI in education It helps researchers practitioners professionals and academicians of various scientific disciplines explore and better comprehend the state of the art of maker education AI and IER their advancements impact and future potentials in education   **Intelligent Robots and Drones for Precision Agriculture** Sundaravadivazhagan Balasubramanian,Gnanasankaran Natarajan,Pethuru Raj Chelliah,2024-03-20 This book provides extensive information about smart farming precision agriculture and the technologies that make them succeed The authors provide detailed machine learning and deep learning models and algorithms that can be implemented effectively to improve smart farming methods The authors also give elaborate information about the various IoT devices and types of drones that are used vastly in smart farming culture The authors show specifically how methods and techniques used to improve the crop yield can be executed to help the farmers to improve the agricultural process and cultivation methods using a rule based methodology The purpose of this book is to articulate the need for processes platforms practices patterns and rules to be followed for the better yield of crop production and how IoT robotics and drones can be used to improve the economy of the countries in the field of agriculture In a nutshell the book shows how the combination of multiple cutting edge technologies leads to the realization of state of the art infrastructures for next generation agriculture   Intelligent Robots and Cobots V. Ramasamy,S. Balamurugan,Sheng-Lung Peng,2025-01-22 The book provides a comprehensive study of how new technological advances utilize robots and Cobots collaborative robots that work safely alongside humans to increase manufacturing efficiency Industry 5 0 focuses on using collaborative robots or cobots enabling users to design with greater freedom This book structured into 18 chapters and three sections Fundamentals Applications and Challenges reflect the current and emerging market trends that shape industrial growth Each chapter explores how businesses incorporating hardware and software like AI cognitive computing blockchain IIoT and more are capitalizing on these innovations to maintain a competitive edge The research and development in the areas of technology has increased the cost effectiveness and acceptance of these IoT enabled devices in many different industries Various sectors including manufacturing healthcare transportation and agriculture sectors have begun incorporating robots and cobots into their operations They are aiming to increase their productivity reduce the downtime of their equipment and optimize resource utilization The individual chapters examine the following subjects Investigation on Deployment of Microservices for Swarm Intelligence of Collaborative Robots Cobot Aided System for Hydroponically Grown Plants Low No Code Software Development of Cobots Using Advanced Graphical User Interface Role of Cobots Over Industrial Robots in Industry 5 0 Activities Cobot Collaboration in the Healthcare Industry

Robotic Arm for Industry Automation Artificial Intelligence Driven Cobots for Innovative Industry 5 0 Workforce Comprehensive Analysis on Design Working and Manufacturing of Soft Robots Workforce for Industry 5 0 The Work of Future and the Future of Work Security Issues and Trends of Industrial Robots and Cobots Aviation Bots for Decongesting Airports Self Contained Study and Evolution of Cobots in Intelligent Transportation Systems Smart Architecture for Data Analytics in Collaborative Robots Contribution of Blockchain Technology for the Cobot s Cybersecurity Issues Security Issues and Trends of Industrial Robots and Cobots Cloud Based Cobots for Industry 5 0 A Human Centric Solution Future Workforce for Industry 5 0 Audience The book s primary audience is researchers and post graduate students in robotics and cobots industrial engineers production and manufacturing engineers working on artificial intelligence and logistics **Emergence of Cyber Physical System and IoT in Smart Automation and Robotics** Krishna Kant Singh,Anand Nayyar,Sudeep Tanwar,Mohamed Abouhawwash,2021-05-04 Cyber Physical Systems CPS integrate computing and communication capabilities by monitoring and controlling the physical systems via embedded hardware and computers This book brings together new and futuristic findings on IoT Cyber Physical Systems and Robotics leading towards Automation and solving issues of various critical applications in Real time The book initially overviews the concepts of IoT IIoT and Cyber Physical Systems followed by various critical applications and discusses the latest designs and developments that provide common solutions for the convergence of technologies In addition the book specifies methodologies algorithms and other relevant architectures in various fields that include Automation Robotics Smart Agriculture and Industry 4 0 The book is intended for practitioners enterprise representatives scientists students and Ph D Scholars in hopes of steering research further towards cyber physical systems design and development and implementation across various domains Additionally this book can be used as a secondary reference or rather one stop guide by professionals for real life implementation of cyber physical systems The book highlights A Critical Coverage of various domains IoT Cyber Physical Systems Industry 4 0 Smart Automation and related critical applications Advanced elaborations for target audiences to understand the conceptual methodology and future directions of cyber physical systems and IoT An approach towards Research Orientations to enable researchers to point out areas and scope for implementation of Cyber Physical Systems in several domains for better productivity *Innovations in the Industrial Internet of Things (IIoT) and Smart Factory* Goundar, Sam,Avanija, J.,Sunitha, Gurram,Madhavi, K. Reddy,Bhushan, S. Bharath,2021-01-22 Industrial internet of things IIoT is changing the face of industry by completely redefining the way stakeholders enterprises and machines connect and interact with each other in the industrial digital ecosystem Smart and connected factories in which all the machinery transmits real time data enable industrial data analytics for improving operational efficiency productivity and industrial processes thus creating new business opportunities asset utilization and connected services IIoT leads factories to step out of legacy environments and arcane processes towards open digital industrial ecosystems Innovations in the Industrial Internet of Things IIoT and Smart

Factory is a pivotal reference source that discusses the development of models and algorithms for predictive control of industrial operations and focuses on optimization of industrial operational efficiency rationalization automation and maintenance While highlighting topics such as artificial intelligence cyber security and data collection this book is ideally designed for engineers manufacturers industrialists managers IT consultants practitioners students researchers and industrial industry professionals **Biologically Inspired Intelligent Robots** Yoseph Bar-Cohen,Cynthia L. Breazeal,2003 The multidisciplinary issues involved in the development of biologically inspired intelligent robots include materials actuators sensors structures functionality control intelligence and autonomy This book reviews various aspects ranging from the biological model to the vision for the future Smart Robots V. Daniel Hunt,1985 Special Robot Technology Tongying Guo,Hui Zhang,Lincang Zhu,2023-05-23 This book focuses on the core technologies of special robots Both principles and engineering practice have been addressed This is achieved by providing an in depth study on several major topics such as the vision positioning of mobile robots the autonomous motion control of ruin search and rescue robots and typical applications of text questions and answers robots The autonomous motion control technologies of ruin search and rescue robots and typical applications of text questions and answers robots are the major features of the book The book benefits researchers engineers senior undergraduate students and postgraduate students in the fields of visual positioning path planning autonomous motion control and typical applications of special robots Rights for Intelligent Robots? Kęstutis Mosakas,2024-08-28 In recent years the question of human moral duties toward robots has gained momentum in scholarly research due to great advancements in the fields of artificial intelligence AI and robotics Although the current machines fall short of the level of sophistication and human likeness portrayed in science fiction e g the Westworld series or the movie Blade Runner 2049 they are increasingly assuming roles in our society in various important areas including manufacturing healthcare education customer service entertainment and many others This book makes a meaningful contribution to the ongoing philosophical discourse surrounding the moral treatment of robots By providing a rigorous and systematic examination of key moral concepts e g moral rights moral status moral considerability and moral value within the context of robotics and exploring other closely related issues e g the moral implications of artificial consciousness and the associated epistemic challenges this book offers fresh insights into the necessary and sufficient conditions for machine moral status and rights *Robotics, Computer Vision and Intelligent Systems* Péter Galambos,Erdal Kayacan,Kurosh Madani,2022-11-09 This volume constitutes the papers of two workshops which were held in conjunctionwith the First International Conference on Robotics Computer Vision and Intelligent Systems ROBOVIS 2020 Virtual Event in November 4 6 2020 and Second International Conference on Robotics Computer Vision and Intelligent Systems ROBOVIS 2021 Virtual Event in October 25 27 2021 The 11 revised full papers presented in this book were carefully reviewed and selectedfrom 53 submissions **Human-Centric Smart Manufacturing Towards Industry 5.0** Baicun Wang,Pai Zheng,Lihui Wang,Dimitris

Mourtzis,2025-05-13 This book presents a set of innovative solutions to human centric manufacturing systems offering critical insights and comprehensive application guidelines for understanding how to realize human centric smart manufacturing by exerting its power and influence towards Industry 5 0 While human centric manufacturing possesses a substantial and growing body of knowledge there are distinct research gaps that are not sufficiently addressed With the development of enabling technologies it is necessary to propose more precise robust and practical approaches in support of smart manufacturing towards Industry 5 0 As a response to the new research opportunities this book presents and highlights the latest development on applying advanced techniques in human centric manufacturing The book will be of interest to a broad readership from academic researchers to practicing engineers   Intelligent Robotics and Applications Zhiyong Chen,Alexandre Mendes,Yamin Yan,Shifeng Chen,2018-08-03 The two volume set LNAI 10984 and LNAI 10985 constitutes the refereed proceedings of the 11th International Conference on Intelligent Robotics and Applications ICIRA 2018 held in Newcastle NSW Australia in August 2018 The 81 papers presented in the two volumes were carefully reviewed and selected from 129 submissions The papers in the first volume of the set are organized in topical sections on multi agent systems and distributed control human machine interaction rehabilitation robotics sensors and actuators and industrial robot and robot manufacturing The papers in the second volume of the set are organized in topical sections on robot grasping and control mobile robotics and path planning robotic vision recognition and reconstruction and robot intelligence and learning   **Advances in Intelligent Robotics and Collaborative Automation** Richard Duro,Yuriy Kondratenko,2022-09-01 This book provides an overview of a series of advanced research lines in robotics as well as of design and development methodologies for intelligent robots and their intelligent components It represents a selection of extended versions of the best papers presented at the Seventh IEEE International Workshop on Intelligent Data Acquisition and Advanced Computing Systems Technology and Applications IDAACS 2013 that were related to these topics Its contents integrate state of the art computational intelligence based techniques for automatic robot control to novel distributed sensing and data integration methodologies that can be applied to intelligent robotics and automation systems The objective of the text was to provide an overview of some of the problems in the field of robotic systems and intelligent automation and the approaches and techniques that relevant research groups within this area are employing to try to solve them The contributions of the different authors have been grouped into four main sections Robots Control and Intelligence Sensing Collaborative automationThe chapters have been structured to provide an easy to follow introduction to the topics that are addressed including the most relevant references so that anyone interested in this field can get started in the area   **Intelligent Robotics and Applications** Xin-Jun Liu,Zhenguo Nie,Jingjun Yu,Fugui Xie,Rui Song,2021-10-19 The 4 volume set LNAI 13013 13016 constitutes the proceedings of the 14th International Conference on Intelligent Robotics and Applications ICIRA 2021 which took place in Yantai China during October 22 25 2021 The 299 papers included in these proceedings were

carefully reviewed and selected from 386 submissions They were organized in topical sections as follows Robotics dexterous manipulation sensors actuators and controllers for soft and hybrid robots cable driven parallel robot human centered wearable robotics hybrid system modeling and human machine interface robot manipulation skills learning micro_nano materials devices and systems for biomedical applications actuating sensing control and instrumentation for ultra precision engineering human robot collaboration robotic machining medical robot machine intelligence for human motion analytics human robot interaction for service robots novel mechanisms robots and applications space robot and on orbit service neural learning enhanced motion planning and control for human robot interaction medical engineering   Intelligent Robotics and Applications Honghai Liu,Naoyuki Kubota,Xiangyang Zhu,Rüdiger Dillmann,Dalin Zhou,2015-08-19 This three volume set LNAI 9244 9245 and 9246 constitutes the refereed proceedings of the 8th International Conference on Intelligent Robotics and Applications ICIRA 2015 held in Portsmouth UK in August 2015 The 46 papers included in the third volume are organized in topical sections on mobile robots and intelligent autonomous systems intelligent system and cybernetics robot mechanism and design robotic vision recognition and reconstruction and active control in tunneling boring machine

   Intelligent Control of Robotic Systems D. Katic,M. Vukobratovic,2013-03-14 As robotic systems make their way into standard practice they have opened the door to a wide spectrum of complex applications Such applications usually demand that the robots be highly intelligent Future robots are likely to have greater sensory capabilities more intelligence higher levels of manual dexter ity and adequate mobility compared to humans In order to ensure high quality control and performance in robotics new intelligent control techniques must be developed which are capable of coping with task complexity multi objective decision making large volumes of perception data and substantial amounts of heuristic information Hence the pursuit of intelligent autonomous robotic systems has been a topic of much fascinating research in recent years On the other hand as emerging technologies Soft Computing paradigms consisting of complementary elements of Fuzzy Logic Neural Computing and Evolutionary Computation are viewed as the most promising methods towards intelligent robotic systems Due to their strong learning and cognitive ability and good tolerance of uncertainty and imprecision Soft Computing techniques have found wide application in the area of intelligent control of robotic systems   **Design and Control of Intelligent Robotic Systems** Dikai Liu,Lingfeng Wang,Kay Chen Tan,2009-01-22 With the increasing applications of intelligent robotic systems in various elds the sign and control of these systems have increasingly attracted interest from researchers This edited book entitled Design and Control of Intelligent Robotic Systems in the book series of Studies in Computational Intelligence is a collection of some advanced research on design and control of intelligent robots The works presented range in scope from design methodologies to robot development Various design approaches and al rithms such as evolutionary computation neural networks fuzzy logic learning etc are included We also would like to mention that most studies reported in this book have been implemented in physical systems An overview on the applications of

computational intelligence in bio inspired robotics is given in Chapter 1 by M Begum and F Karray with highlights of the recent progress in bio inspired robotics research and a focus on the usage of computational intelligence tools to design human like cognitive abilities in the robotic systems In Chapter 2 Lisa L Grant and Ganesh K Venayagamoorthy present greedy search particle swarm optimization and fuzzy logic based strategies for navigating a swarm of robots for target search in a hazardous environment with potential applications in high risk tasks such as disaster recovery and hazardous material detection

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