

Technology Development for Army Unmanned Ground Vehicles



Technology Development For Army Unmanned Ground Vehicles Paperback

Christian Drosten



Technology Development For Army Unmanned Ground Vehicles Paperback:

Technology Development for Army Unmanned Ground Vehicles National Research Council, Division on Engineering and Physical Sciences, Board on Army Science and Technology, Committee on Army Unmanned Ground Vehicle Technology, 2003-02-01 Unmanned ground vehicles UGV are expected to play a key role in the Army's Objective Force structure. These UGVs would be used for weapons platforms, logistics carriers, and reconnaissance, surveillance, and target acquisition among other things. To examine aspects of the Army's UGV program, assess technology readiness, and identify key issues in implementing UGV systems among other questions, the Deputy Assistant Secretary of the Army for Research and Technology asked the National Research Council (NRC) to conduct a study of UGV technologies. This report discusses UGV operational requirements, current development efforts, and technology integration and roadmaps to the future. Key recommendations are presented, addressing technical content, time lines, and milestones for the UGV efforts. **Technology**

Development for Army Unmanned Ground Vehicles, 2002 [The Quest for Artificial Intelligence](#) Nils J.

Nilsson, 2009-10-30 Artificial intelligence (AI) is a field within computer science that is attempting to build enhanced intelligence into computer systems. This book traces the history of the subject from the early dreams of eighteenth-century and earlier pioneers to the more successful work of today's AI engineers. AI is becoming more and more a part of everyone's life. The technology is already embedded in face recognizing cameras, speech recognition software, Internet search engines, and health care robots among other applications. The book's many diagrams and easy-to-understand descriptions of AI programs will help the casual reader gain an understanding of how these and other AI systems actually work. Its thorough but unobtrusive end-of-chapter notes containing citations to important source materials will be of great use to AI scholars and researchers. This book promises to be the definitive history of a field that has captivated the imaginations of scientists, philosophers, and writers for centuries. *From Automated to Autonomous Driving* Fabian Kröger, 2024-04-01 This book

presents the most important milestones of the research on automated and autonomous driving in the United States, Japan, and Europe throughout five decades (1950-2000). Drawing on sources from the automotive industry, electrical engineering, the robotics and AI domain, and military institutions, it retraces the transition from the guidance cable approach to vehicle-based sensor and vision systems. Giving a detailed overview of the technical concepts, artifacts, research vehicles, and robots, the book presents the transnational engineering efforts that started long before Silicon Valley entered the field. In addition, the book also uniquely details the role of the military in the domain of vehicle automation. This all ensures the book is of great interest to historians of technology, practitioners in engineering disciplines, scholars working in mobility studies, journalists, and political decision makers. *The Rise of Unmanned Warfare* Jacquelyn Schneider, MacDonald, 2023-12-15 What explains the current US arsenal of unmanned systems? Why, for example, is the contemporary arsenal dominated by aerial unmanned systems versus the munitions that dominated earlier developments? This book challenges traditional explanations for the

proliferation of unmanned systems which focus on capacity or structure. Instead, this book argues that beliefs and identities shape the structures and capacities we choose when we are investing in weapon systems. In particular, it traces beliefs about technological determinism and military revolutions, force protection and casualty aversion, and service identities to explain why the US has invested so heavily in remote controlled unmanned aerial platforms over the last three decades. In doing so, the book illustrates how ideas become influence and ultimately manifest in budget lines, detailing the policy entrepreneurs' critical junctures and path dependencies that shape the lifecycle of beliefs about unmanned weapon systems. The book begins by providing a historical overview of US unmanned systems investments, taking an expansive view of unmanned technologies from land mines to missiles and drones from the revolutionary war to contemporary investments. It then leans on theories of norms, ideas, and influence to detail the role of the Office of Net Assessment, Vietnam 9/11, and armed service identity in building the US current unmanned arsenal. Finally, it concludes with what this case of unmanned technologies reveals about US support to Ukraine, as well as contemporary weapons debates about cyber information technology, space, and hypersonic missiles.

Innovations in Defence Support Systems - 1 Anthony Finn, 2010-07-15. Innovations in the area of Defence Support Systems are multi-disciplinary, cover a broad range of technologies, and could not possibly be covered within a single volume. This research book presents a sample of research as below: On the Transition of Innovation and Technology in Defence; Inserting Innovations in Service; Classification of Battlefield Ground Vehicles based on the Acoustic Emissions Convoy Movement Problem; An Optimization Perspective; Machine Vision Algorithms for Autonomous Aerial Refueling for UAVs using the USAF Refueling Boom Method; Motion Optimization Scheme for Cooperative Mobile Robots; An Automated Decision System for Landmine Detection and Classification. The book is directed to the application engineers, research students, professors, decision makers, and scientists/engineers working in defence and related areas.

Technology for Small Spacecraft National Research Council, Division on Engineering and Physical Sciences, Commission on Engineering and Technical Systems, Panel on Small Spacecraft Technology, 1994-02-01. This book reviews the U.S. National Aeronautics and Space Administration's NASA small spacecraft technology development. Included are assessments of NASA's technology priorities for relevance to small spacecraft and identification of technology gaps and overlaps. The volume also examines the small spacecraft technology programs of other government agencies and assesses technology efforts in industry.

Unmanned Ground Vehicle Technology, 2005. *Reducing the Logistics Burden for the Army After Next* National Research Council, Division on Engineering and Physical Sciences, Commission on Engineering and Technical Systems, Committee to Perform a Technology Assessment Focused on Logistics Support Requirements for Future Army Combat Systems, 1999-04-22. This study assesses the potential of new technology to reduce logistics support requirements for future Army combat systems. It describes and recommends areas of research and technology development in which the Army should invest now to field systems that will reduce logistics burdens and provide desired capabilities for an Army After Next.

AAN battle force in 2025 *Vision Based Systems for UAV Applications* Aleksander Nawrat, Zygmunt Kuś, 2013-12-06 This monograph is motivated by a significant number of vision based algorithms for Unmanned Aerial Vehicles UAV that were developed during research and development projects Vision information is utilized in various applications like visual surveillance aim systems recognition systems collision avoidance systems and navigation This book presents practical applications examples and recent challenges in these mentioned application fields The aim of the book is to create a valuable source of information for researchers and constructors of solutions utilizing vision from UAV Scientists researchers and graduate students involved in computer vision image processing data fusion control algorithms mechanics data mining navigation and IC can find many valuable useful and practical suggestions and solutions The latest challenges for vision based systems are also presented **Army Robotics and Artificial Intelligence** Commission On Engineering and Technic Committee to Review Army Robotics and Artificial Intelligenc, 1987-01-15 Army AL & T, 2004 Print & Digital Federal Publications Catalog, 2014 Advanced Autonomous Vehicle Design for Severe Environments V.V. Vantsevich, M.V. Blundell, 2015-10-20 Classical vehicle dynamics which is the basis for manned ground vehicle design has exhausted its potential for providing novel design concepts to a large degree At the same time unmanned ground vehicle UGV dynamics is still in its infancy and is currently being developed using general analytical dynamics principles with very little input from actual vehicle dynamics theory This technical book presents outcomes from the NATO Advanced Study Institute ASI Advanced Autonomous Vehicle Design for Severe Environments held in Coventry UK in July 2014 The ASI provided a platform for world class professionals to meet and discuss leading edge research engineering accomplishments and future trends in manned and unmanned ground vehicle dynamics terrain mobility and energy efficiency The outcomes of this collective effort serve as an analytical foundation for autonomous vehicle design Topics covered include historical aspects pivotal accomplishments and the analysis of future trends in on and off road manned and unmanned vehicle dynamics terramechanics soil dynamic characteristics uncertainties and stochastic characteristics of vehicle environment interaction for agile vehicle dynamics modeling new methods and techniques in on line control and learning for vehicle autonomy fundamentals of agility and severe environments mechatronics and cyber physics issues of agile vehicle dynamics to design for control energy harvesting and cyber security and case studies of agile and inverse vehicle dynamics and vehicle systems design including optimisation of suspension and driveline systems The book targets graduate students who desire to advance further in leading edge vehicle dynamics topics in manned and unmanned ground vehicles PhD students continuing their research work and building advanced curricula in academia and industry and researchers in government agencies and private companies *Path Planning for Autonomous Vehicle* Umar Zakir Abdul Hamid, Volkan Sezer, Bin Li, Yanjun Huang, Muhammad Aizzat Zakaria, 2019-10-02 Path Planning PP is one of the prerequisites in ensuring safe navigation and manoeuvrability control for driverless vehicles Due to the dynamic nature of the real world PP needs to address changing

environments and how autonomous vehicles respond to them This book explores PP in the context of road vehicles robots off road scenarios multi robot motion and unmanned aerial vehicles UAVs **Signal** ,2010 **Autonomous Vehicles in Support of Naval Operations** National Research Council,Division on Engineering and Physical Sciences,Naval Studies Board,Committee on Autonomous Vehicles in Support of Naval Operations,2005-08-05 Autonomous vehicles AVs have been used in military operations for more than 60 years with torpedoes cruise missiles satellites and target drones being early examples 1 They have also been widely used in the civilian sector for example in the disposal of explosives for work and measurement in radioactive environments by various offshore industries for both creating and maintaining undersea facilities for atmospheric and undersea research and by industry in automated and robotic manufacturing Recent military experiences with AVs have consistently demonstrated their value in a wide range of missions and anticipated developments of AVs hold promise for increasingly significant roles in future naval operations Advances in AV capabilities are enabled and limited by progress in the technologies of computing and robotics navigation communications and networking power sources and propulsion and materials Autonomous Vehicles in Support of Naval Operations is a forward looking discussion of the naval operational environment and vision for the Navy and Marine Corps and of naval mission needs and potential applications and limitations of AVs This report considers the potential of AVs for naval operations operational needs and technology issues and opportunities for improved operations **Autonomous Mobile Robots** Frank L. Lewis,Shuzhi Sam Ge,2018-10-03 It has long been the goal of engineers to develop tools that enhance our ability to do work increase our quality of life or perform tasks that are either beyond our ability too hazardous or too tedious to be left to human efforts Autonomous mobile robots are the culmination of decades of research and development and their potential is seemingly unlimited Roadmap to the Future Serving as the first comprehensive reference on this interdisciplinary technology Autonomous Mobile Robots Sensing Control Decision Making and Applications authoritatively addresses the theoretical technical and practical aspects of the field The book examines in detail the key components that form an autonomous mobile robot from sensors and sensor fusion to modeling and control map building and path planning and decision making and autonomy and to the final integration of these components for diversified applications Trusted Guidance A duo of accomplished experts leads a team of renowned international researchers and professionals who provide detailed technical reviews and the latest solutions to a variety of important problems They share hard won insight into the practical implementation and integration issues involved in developing autonomous and open robotic systems along with in depth examples current and future applications and extensive illustrations For anyone involved in researching designing or deploying autonomous robotic systems Autonomous Mobile Robots is the perfect resource *Advanced Land Warfare* Mikael Weissmann,Niklas Nilsson,2023-03-23 International politics have become ever more volatile over the last decade increasing the risk of large scale military violence Yet the precise character of future war will depend on a range of factors that relate to adversaries allies technology geographical

scope and multiple domains of warfighting Few would question that land forces will be important also in the foreseeable future However given that the battlefield is in a state of transformation so is the mission purpose and utilization of land forces Indeed the future conduct of land warfare is subjected to serious and important questions in the face of large and complex challenges and security threats Advanced Land Warfare explores the evolving role of land forces paying particular attention to the changes that have taken place in the art of commanding and executing combat as well as the role of rapid technological innovation and information dissemination in shaping warfare The book provides insights into key contemporary developments in land warfare and presents case studies on land tactics and operations in different national contexts drawing on the best of theory practice and professional experience and featuring chapters written by leading international scholars and practitioners Relating to the realities of the modern battlefield the book addresses a number of critical questions about land tactics and operations combining a conceptual basis with empirical examples of tactical thinking and practice and emphasising the importance of understanding the perspectives of various national armies in order to provide a current understanding of the central issues of land warfare An open access title available under the terms of a CC BY NC ND 4 0 International licence **Books In Print 2004-2005** Ed Bowker Staff,Staff Bowker, Ed,2004

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