# COMPUTER ARCHITECTURES FOR ROBOTICS AND AUTOMATION

Edited by JAMES H. GRAHAM



# **Specialized Computer Architectures For Robotics And Automation**

**B** Lingard

#### **Specialized Computer Architectures For Robotics And Automation:**

**Computer Architectures for Robotics and Automation** James H. Graham, 1987 Addresses the important topic of providing adequate computational power for the demanding real time requirements of advanced robotic systems Shows how many of the recent advances in image processing control and machine intelligence can be incorporated into robotic systems in real time Explains how innovative specialized computer architectures that include both parallelism and special purpose hardware can speed the development of robot potential **Cluster Computing for Robotics and Computer Vision** Damian M. Lyons, 2011 In this book we look at how cluster technology can be leveraged to build better robots Algorithms and approaches in key areas of robotics and computer vision such as map building target tracking action selection and landmark learning are reviewed and cluster implementations for these are presented The objective of the book is to give professionals working in the beowulf cluster or robotics and computer vision fields a concrete view of the strong synergy between the areas as well as to spur further fruitful exploitation of this connection. The book is written at a level appropriate for an advanced undergraduate or graduate student The key concepts in robotics computer vision and cluster computing are introduced before being used to make the text useful to a wide audience in these fields **Distributed Autonomous** Robotic Systems 3 Tim Lueth, Rüdiger Dillmann, Paolo Dario, Heinz Wörn, 2012-12-06 Distributed autonomous robotic systems DARS are systems composed of multiple autonomous units such as modules cells processors agents and robots Combination or cooperative operation of multiple autonomous units is expected to lead to desirable features such as flexibility fault tolerance and efficiency The DARS is the leading established conference on distributed autonomous systems All papers have the common goal to contribute solutions to the very demanding task of designing distributed systems to realize robust and intelligent robotic systems **Architectural Design** Chris A. Vissers, Luís Ferreira Pires, Dick A.C. Quartel, Marten van Sinderen, 2016-09-30 This book presents a design methodology that is practically applicable to the architectural design of a broad range of systems It is based on fundamental design concepts to conceive and specify the required functional properties of a system while abstracting from the specific implementation functions and technologies that can be chosen to build the system Abstraction and precision are indispensable when it comes to understanding complex systems and precisely creating and representing them at a high functional level Once understood these concepts appear natural self evident and extremely powerful since they can directly precisely and concisely reflect what is considered essential for the functional behavior of a system The first two chapters present the global views on how to design systems and how to interpret terms and meta concepts This informal introduction provides the general context for the remainder of the book On a more formal level Chapters 3 through 6 present the main basic design concepts illustrating them with examples Language notations are introduced along with the basic design concepts Lastly Chapters 7 to 12 discuss the more intricate basic design concepts of interactive systems by focusing on their common functional goal These chapters are

recommended to readers who have a particular interest in the design of protocols and interfaces for various systems The didactic approach makes it suitable for graduate students who want to develop insights into and skills in developing complex systems as well as practitioners in industry and large organizations who are responsible for the design and development of large and complex systems It includes numerous tangible examples from various fields and several appealing exercises with **Recent Trends in Mobile Robots** Yuan-Fang Zheng, 1993 This book presents recent trends in the field as perceived by a global selection of researchers and experts Subjects covered include motion planning of mobile robots in unknown environments coordination between mobility and manipulability computation environments for mobile robots nonlinear control of mobile robots and environmental modeling using advanced sensing technologies Issues ranging from progress in applications to fundamental problems are discussed Modelling and Identification in Robotics Krzysztof R. Kozlowski, 2012-12-06 As the use and relevance of robotics for countless scientific purposes grows all the time research into the many diverse elements of the subject becomes ever more important and in demand This volume examines in depth the most topical complex issues of modelling and identification in robotics. The book is divided into three main parts. The first part is devoted to robot dynamics modelling and identification of robot and load parameters incorporating friction torques discussing identification schemes and presenting simulations and experiment all results of robot and load dynamic parameters identification A general concept of robot programming language for research and educational purposes is examined and there is a detailed outline of its basic structures along with hardware requirements which both constitute an open robot controller architecture Finally a hybrid controller is derived and several experimental results of this system are outlined This impressive discussion of the topic covers both the theoretical and practical illustrated throughout by examples and experimental results and will be of value to anyone researching or practising within the field of robotics automation and 1993 Computer Architectures for Machine Perception Magdy A. system i dentification or to control engineers Bayoumi, Larry S. Davis, Kimon Valavanis, 1993 Proceedings of the Computer Architectures for Machine Perception Workshop held Dec 15 17 1993 in New Orleans Louisiana Papers came from several communities computer architecture pattern recognition image processing and analysis computer vision and VLSI No index Annotation copyright Book N **Computation Systems for Robotics** A. Fijany, 1992 This book presents an extensive survey of the state of the art research in parallel computational algorithms and architectures for robot manipulator control and simulation It deals not only with specifics but also includes general and broader issues which serve as a useful foundation to the topic The educational flavor of the book makes it a necessary resource for researchers engineers and students wanting to be familiarized with the potential offered by the application of parallel processing to robotic problems and its current issues and trends Fourth **Euromicro Workshop on Real-Time Systems** ,1992 NBS Special Publication ,1977

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