

Paul J. Besl

Surfaces in Range Image Understanding



Springer-Verlag

Surfaces In Range Image Understanding Series In Perception Engineering

Kazuhiko Sumi



Surfaces In Range Image Understanding Series In Perception Engineering:

Surfaces in Range Image Understanding Paul J. Besl, 2012-12-06 Machine perception requires the digitization of physically sensed signals During the last ten years digital range images have become available from a variety of sensors This book is devoted to the problem of range image understanding with computers Its aims are to develop a theoretical framework devise appropriate algorithms and demonstrate a software implementation of those algorithms that will confirm the usefulness of surfaces in range image understanding It will be of interest to the researcher studying the theoretical concepts of image understanding as well as the engineer who wants to implement these concepts in practical applications

Surfaces In Range Image Understanding P.J. Besl, **Analysis and Interpretation of Range Images** Ramesh C. Jain, Anil K. Jain, 2012-12-06 Computer vision researchers have been frustrated in their attempts to automatically derive depth information from conventional two dimensional intensity images Research on shape from texture shape from shading and shape from focus is still in a laboratory stage and had not seen much use in commercial machine vision systems A range image or a depth map contains explicit information about the distance from the sensor to the object surfaces within the field of view in the scene Information about surface geometry which is important for say three dimensional object recognition is more easily extracted from 2 1 2 D range images than from 2D intensity images As a result both active sensors such as laser range finders and passive techniques such as multi camera stereo vision are being increasingly utilized by vision researchers to solve a variety of problems This book contains chapters written by distinguished computer vision researchers covering the following areas Overview of 3D Vision Range Sensing Geometric Processing Object Recognition Navigation Inspection Multisensor Fusion A workshop report written by the editors also appears in the book It summarizes the state of the art and proposes future research directions in range image sensing processing interpretation and applications The book also contains an extensive up to date bibliography on the above topics This book provides a unique perspective on the problem of three dimensional sensing and processing it is the only comprehensive collection of papers devoted to range images Both academic researchers interested in research issues in 3D vision and industrial engineers in search of solutions to particular problems will find this a useful reference book **Advances In Visual Form Analysis: Proceedings Of The 3rd**

International Workshop On Visual Form Gabriella Sanniti Di Baja, Carlo Arcelli, Luigi P Cordella, 1997-10-31 This volume contains papers presented at the Third International Workshop on Visual Form It covers the most important topics of current interest in the field presenting an updated collection of results achieved by leading academic and industrial research groups from several countries The book contains invited lectures and research papers dealing with theoretical and applicative aspects of shape perception representation decomposition description and recognition as well as related topics

Describing and Recognizing 3-D Objects Using Surface Properties Ting-Jun Fan, 2012-12-06 Surface properties play a very important role in many perception tasks Object recognition navigation and inspection use surface properties ex

tensively Characterizing surfaces at different scales in given data is often the first and possibly the most important step Most early research in machine perception relied on only very coarse characterization of surfaces In the last few years surface characterization has been receiving due attention Dr T J Fan is one of the very few researchers who designed and implemented a complete system for object recognition He studied issues related to characterization of surfaces in the context of object recognition and then uses the features thus developed for recognizing objects He uses a multi view representation of 3 D objects for recognition and he develops techniques for the segmentation of range images to obtain features for recognition His matching approach also allows him to recognize objects from their partial views in the presence of other occluding objects The efficacy of his approach is demonstrated in many examples High-Speed Range Estimation Based on Intensity Gradient Analysis Kurt D. Skifstad,2012-12-06 A fast and reasonably accurate perception of the environment is essential for successful navigation of an autonomous agent Although many modes of sensing are applicable to this task and have been used vision remains the most appealing due to its passive nature good range and resolution Most vision techniques to recover depth for navigation use stereo In the last few years researchers have started studying techniques to combine stereo with the motion of the camera Skifstad's dissertation proposes a new approach to recover depth information using known camera motion This approach results in a robust technique for fast estimation of distances to objects in an image using only one translating camera A very interesting aspect of the approach pursued by Skifstad is the method used to bypass the most difficult and computationally expensive step in using stereo or similar approaches for the vision based depth estimation The correspondence problem has been the focus of research in most stereo approaches Skifstad trades the correspondence problem for the known translational motion by using the fact that it is easier to detect single pixel disparities in a sequence of images rather than arbitrary disparities after two frames A very attractive feature of this approach is that the computations required to detect single pixel disparities are local and hence can be easily parallelized Another useful feature of the approach particularly in navigation applications is that the closer objects are detected earlier Vision-based Vehicle Guidance Ichiro Masaki,2012-12-06 There is a growing social interest in developing vision based vehicle guidance systems for improving traffic safety and efficiency and the environment Examples of vision based vehicle guidance systems include collision warning systems steering control systems for tracking painted lane marks and speed control systems for preventing rear end collisions Like other guidance systems for aircraft and trains these systems are expected to increase traffic safety significantly For example safety improvements of aircraft landing processes after the introduction of automatic guidance systems have been reported to be 100 times better than prior to installment Although the safety of human lives is beyond price the cost for automatic guidance could be compensated by decreased insurance costs It is becoming more important to increase traffic safety by decreasing the human driver's load in our society especially with an increasing population of senior people who continue to drive The second potential social benefit is the improvement of traffic efficiency

by decreasing the spacing between vehicles without sacrificing safety It is reported for example that four times the efficiency is expected if the spacing between cars is controlled automatically at 90 cm with a speed of 100 km/h compared to today's typical manual driving Although there are a lot of technical psychological and social issues to be solved before realizing the high density high speed traffic systems described here highly efficient highways are becoming more important because of increasing traffic congestion

Image Analysis Rasmus R. Paulsen, Kim S. Pedersen, 2015-06-08 This book constitutes the refereed proceedings of the 19th Scandinavian Conference on Image Analysis SCIA 2015 held in Copenhagen Denmark in June 2015 The 45 revised papers presented were carefully reviewed and selected from 67 submissions The contributions are structured in topical sections on novel applications of vision systems pattern recognition machine learning feature extraction segmentation 3D vision to medical and biomedical image analysis

Multiresolution Image Shape Description John M. Gauch, 2012-12-06 Much of our understanding of the relationships among geometric structures in images is based on the shape of these structures and their relative orientations positions and sizes Thus developing quantitative methods for capturing shape information from digital images is an important area for computer vision research This book describes the theory implementation and application of two multi resolution image shape description methods The author begins by motivating the need for quantitative methods for describing both the spatial and intensity variations of structures in grey scale images Two new methods which capture this information are then developed The first the intensity axis of symmetry is a collection of branching and bending surfaces which correspond to the skeleton of the image The second method multiresolution vertex curves focuses on surface curvature properties as the image is blurred by a sequence of Gaussian filters Implementation techniques for these image shape descriptions are described in detail Surface functionals are minimized subject to symmetry constraints to obtain the intensity axis of symmetry Robust numerical methods are developed for calculating and following vertex curves through scale space Finally the author demonstrates how grey scale images can be segmented into geometrically coherent regions using these shape description techniques Building quantitative analysis applications in terms of these visually sensible image regions promises to be an exciting area of biomedical computer vision research

Exploratory Vision Michael S. Landy, Laurence T. Maloney, Misha Pavel, 2012-12-06 Advances in sensing signal processing and computer technology during the past half century have stimulated numerous attempts to design general purpose machines that see These attempts have met with at best modest success and more typically outright failure The difficulties encountered in building working computer vision systems based on state of the art techniques came as a surprise Perhaps the most frustrating aspect of the problem is that machine vision systems cannot deal with numerous visual tasks that humans perform rapidly and effortlessly In reaction to this perceived discrepancy in performance various researchers notably Marr 1982 suggested that the design of machine vision systems should be based on principles drawn from the study of biological

systems This neuro morphic or anthropomorphic approach has proven fruitful the use of pyramid multiresolution image representation methods in image compression is one example of a successful application based on principles primarily derived from the study of biological vision systems It is still the case however that the performance of computer vision systems falls far short of that of the natural systems since they are intended to mimic suggesting that it is time to look even more closely at the remaining differences between artificial and biological vision systems

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